Chapter 8 Digital Modulation in an Additive White Gaussian Noise Baseband Channel (IV)

M-ary Pulse Modulation (1/3)

- We consider the simultaneous transmission of multiple bits by using more than two signal waveforms
- The binary information sequence is subdivided into blocks of k bits, called symbols, and each block (or symbol) is represented by one of M=2^k signal waveforms, each of duration T. This type of modulation is called M-ary modulation
- The signaling (symbol) rate, *R_s*, as the number of signals (or symbols) transmitted per second. Clearly,

$$R_{s}=\frac{1}{T}$$

M-ary Pulse Modulation (2/3)

Each signal carries k=log₂M bits of information, the bit rate is given by

$$R_b = kR_s = \frac{k}{T}$$

• The bit interval is

$$T_b = \frac{1}{R_b} = \frac{T}{k}$$



Figure 8.27 Relationship between the symbol interval and the bit interval.

M-ary Pulse Modulation (3/3)

- The *M* signal waveforms may be one-dimensional or multidimensional
- The one-dimensional *M*-ary signals are a generalization of the binary PAM (antipodal) signals. The multi-dimensional signals are a generalization of the binary PPM (orthogonal) signals

M-ary Pulse Amplitude Modulation (1/5)

The k-bit symbols are used to select M=2^k signal amplitudes.
 The M-ary PAM signal waveforms may be expressed as

$$s_m(t) = A_m g_T(t), \quad 0 \le t \le T, \quad m = 1, 2, ..., M$$

= $s_m \psi(t), \quad 0 \le t \le T, \quad m = 1, 2, ..., M$

• All *M* signal waveforms have the same pulse shape. Hence, they are one-dimensional signals. Note that $s_m = A_m \sqrt{T}$



M-ary Pulse Amplitude Modulation (2/5)

• An important feature of these PAM signals is that they have different energies. That is,

$$\boldsymbol{\mathcal{E}}_{m} = \int_{0}^{T} s_{m}^{2}(t) dt = s_{m}^{2} \int_{0}^{T} \psi^{2}(t) dt = s_{m}^{2} = A_{m}^{2} T$$

Assuming that all k-bit symbols are equally probable, the average energy of the transmitted signals is

$$\boldsymbol{\mathcal{E}}_{av} = \frac{1}{M} \sum_{m=1}^{M} \boldsymbol{\mathcal{E}}_{m} = \frac{T}{M} \sum_{m=1}^{M} \boldsymbol{A}_{m}^{2}$$

• In order to minimize the average transmitted energy and to avoid transmitting signals with a DC component, we want to select the *M* signal amplitudes to be symmetric about the origin and equally spaced. That is,

$$A_m = (2m - 1 - M)A, m = 1, 2, \dots, M$$

M-ary Pulse Amplitude Modulation (3/5)

• The corresponding average energy, assuming that all *k*-bit symbols are equally probable, is

$$\mathcal{E}_{av} = \frac{A^2 T}{M} \sum_{m=1}^{M} (2m - 1 - M)^2$$
$$= A^2 T (M^2 - 1) / 3$$

• The corresponding signal constellation point of the *M*-ary PAM signals are given as $s = A \sqrt{T}$

$$A_m - A_m \sqrt{T}$$

= $A\sqrt{T}(2m-1-M), m = 1, 2, ..., M$

• It is convenient to define the distance parameter d as $d = A\sqrt{T}$, so that

$$s_m = (2m - 1 - M)d, m = 1, 2, \dots, M$$

M-ary Pulse Amplitude Modulation (4/5)

- The signal constellation point diagram is shown in Fig. 8.29. The distance between two adjacent signal points is 2*d*
- **Example 8.4.1.** Sketch the signal waveforms for *M*=4 PAM and determine the average transmitted signal energy.
- The average energy, based on equally probable signals, is

$$\boldsymbol{\mathcal{E}}_{av}=5A^2T=5d^2,$$

where $d^2 = A^2 T$ by definition



Figure 8.29 Signal point constellation for *M*-ary PAM.

M-ary Pulse Amplitude Modulation (5/5)

• Example 8.4.1. (Cont'd) The four signal waveforms are shown in Fig. 8.30



Figure 8.30 M = 4 PAM signal waveforms.

M-ary Orthogonal Signals (1/8)

- *M*-ary orthogonal signal waveforms at baseband can be constructed in a variety of ways. Fig. 8.31 illustrates two sets of M=4 orthogonal signal waveforms, which are represented as $s_i(t)$ and $s_i'(t)$, $i=1,\ldots,4$
- Fig. 8.31(a) and Fig. 8.31(b) both satisfy the orthogonality condition, namely,

$$\int_{0}^{T} s_{i}'(t)s_{j}'(t)dt = 0, \ i \neq j$$

• The number of dimensions required to represent a set of *M* orthogonal waveforms is *N*=*M*. Hence, a set of *M* orthogonal signal waveforms can be represented geometrically by *M* orthogonal vectors in *M*-dimensional space

M-ary Orthogonal Signals (2/8)



Figure 8.31 Two sets of M = 4 orthogonal signal waveforms.

M-ary Orthogonal Signals (3/8)



Figure 8.31 Two sets of M = 4 orthogonal signal waveforms.

M-ary Orthogonal Signals (4/8)

• Consider *M*-ary PPM signal waveforms expressed mathematically as

$$s_m(t) = \sqrt{\boldsymbol{\mathcal{E}}_s} \boldsymbol{\psi}_m(t), \ m = 1, 2, \dots, M$$
,

where $\Psi_m(t)$ and $m=1,2,\ldots,M$ are a set of M orthogonal basis waveforms. These waveform are defined as

$$\Psi_m(t) = g_T(t - \frac{(m-1)T}{M}), \quad \frac{(m-1)T}{M} \le t \le \frac{mT}{M}$$

in which $g_T(t)$ is a unit energy pulse, which is nonzero over the time interval $0 \le t \le \frac{T}{M}$

M-ary Orthogonal Signals (5/8)

• Each signal waveform $s_m(t)$ has energy $\int_0^T {s_m}^2(t) dt = \mathcal{E}_s \int_0^T \psi_m^2(t) dt = \mathcal{E}_s, \text{ all } m$

 $\boldsymbol{\mathcal{E}}_{s}$ denotes the energy of each of the signal waveforms representing *k*-bit symbols

• Note $\Psi_m(t)$ has unit power



Figure 8.32 Rectangular pulse $g_T(t)$ and basis function $\psi_m(t)$ for *M*-ary PPM signal waveforms.

M-ary Orthogonal Signals (6/8)

• *M*-ary PPM signal waveforms are represented geometrically by the following *M*-dimensional vectors

$$\mathbf{s}_1 = (\sqrt{\boldsymbol{\mathcal{E}}_s}, 0, 0, \dots, 0)$$

$$\mathbf{s}_2 = (0, \sqrt{\boldsymbol{\mathcal{E}}_s}, 0, \dots, 0)$$

$$s_M = (0, 0, 0, \cdots, \sqrt{\boldsymbol{\mathcal{E}}_s})$$

- These vectors are orthogonal, *i.e.*, $s_i \cdot s_j = 0$ when $i \neq j$
- The *M* signal vectors are mutually equidistant, *i.e.*, $d_{mn} = || \mathbf{s}_m - \mathbf{s}_n || = \sqrt{2 \mathbf{\mathcal{E}}_s}, \text{ for all } m \neq n$

M-ary Orthogonal Signals (7/8)

- Example 8.4.2. Determine the vectors in a geometric representation of the M=4 signal waveforms $s_i'(t)$ and i=1,2,3,4, that are shown in Fig. 8.31(b). Use the basis waveforms $\psi_m(t)$ that are shown in Fig. 8.32
- Note that the four orthogonal waveforms have equal energy, given by

$$\int_0^T [s_i'(t)]^2 dt = \boldsymbol{\mathcal{E}}_s$$

• By computing the projection of each signal waveform on the four basis waveforms $\psi_m(t)$, *i.e.*,

$$\int_0^T s_i'(t)\psi_m(t)dt, \ m = 1, 2, 3, 4,$$

we obtain the vector s_i '

M-ary Orthogonal Signals (8/8)

• Example 8.4.2. (Cont'd) We obtain

$$s_{1}' = (\sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4})$$

$$s_{2}' = (\sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4})$$

$$s_{3}' = (\sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4})$$

$$s_{4}' = (\sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, -\sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4}, \sqrt{\mathcal{E}_{s}/4})$$

- We observe that these four signal vectors are orthogonal, *i.e.*,
 s_i' s_j'=0, for *i≠j*
- Note that $\|s_i'\|^2 = \mathcal{E}_s$, i=1,2,3,4

The Optimum Demodulator for M-ary Signals in AWGN (1/14)

- We assume that the digital communication system transmits digital information by using any of the *M*-ary signal waveforms described in the preceding sections
- Each of the $M=2^k$ symbols is associated with a corresponding baseband signal waveform from the set $\{s_m(t), m=1, 2, \ldots, M\}$. Each signal waveform is transmitted within the symbol (signaling) interval *T*. We consider the transmission of information over the interval $0 \le t \le T$
- We wish to design a receiver that is optimum in the sense that it minimizes the probability of making an error

The Optimum Demodulator for M-ary Signals in AWGN (2/14)

• The channel is assumed to corrupt the signal by the addition of white Gaussian noise. Thus, the received signal in the interval $0 \leq t \leq T$ may be expressed as

 $r(t) = s_m(t) + n(t), 0 \leq t \leq T$

where n(t) denotes the sample function of the additive white Gaussian noise (AWGN) process with the power spectral density $S_n(f) = N_0/2$

• We subdivide the receiver into two parts: the signal demodulator and the detector. The demodulator converts the received waveform r(t) into an *N*-dimensional vector $y=(y_1,y_2,\ldots,y_N)$, where *N* is the dimension of the transmitted signal waveform

The Optimum Demodulator for M-ary Signals in AWGN (3/14)

- The function of the detector is to decide which of the *M* possible signal waveforms was transmitted based on observation of the vector *y*
- We have shown that the *M*-ary signal waveform, each of which is *N*-dimensional, may be represented in general as

$$s_m(t) = \sum_{k=1}^N s_{mk} \psi_k(t), \ 0 \le t \le T, \ m = 1, 2, ..., M,$$

where $\{s_{mk}\}$ are the coordinates of the signal vector

$$s_m = (s_{m1}, s_{m2}, \dots, s_{mN}), m = 1, 2, \dots, M,$$

and $\psi_k(t)$ and $k=1,2,\ldots,N$ are *N* orthonormal basis waveforms that span the *N*-dimensional signal space

The Optimum Demodulator for M-ary Signals in AWGN (4/14)

- As a generalization of the demodulator for binary signals, we employ either a correlation-type demodulator or a matched-filter-type demodulator
- The correlator outputs at the end of the signal interval is $y_{k} = \int_{0}^{T} r(t)\psi_{k}(t)dt$ $= \int_{0}^{T} [s_{m}(t) + n(t)]\psi_{k}(t)dt$ $= \int_{0}^{T} s_{m}(t)\psi_{k}(t)dt + \int_{0}^{T} n(t)\psi_{k}(t)dt$ $= s_{mk} + n_{k}, \ k = 1, 2, ..., N \qquad (8.4.34)$

• Eq. (8.4.34) is equivalent to

$$y=s_m+n$$
,

where s_m and n are vectors

The Optimum Demodulator for *M*-ary Signals in AWGN (5/14)



Figure 8.39 Correlation-type demodulator.

The Optimum Demodulator for M-ary Signals in AWGN (6/14)

• We can express the received signal r(t) in the interval $0 \le t \le T$ as

$$r(t) = \sum_{k=1}^{N} s_{mk} \psi_k(t) + \sum_{k=1}^{N} n_k \psi_k(t) + n'(t)$$
$$= \sum_{k=1}^{N} y_k \psi_k(t) + n(t)$$

• The term n'(t), defined as

$$n'(t) = n(t) - \sum_{k=1}^{N} n_k \psi_k(t),$$

is a zero-mean Gaussian noise process that represents the difference between the original noise process n(t) and the part that corresponds to the projection of n(t) onto the basis function $\{\psi_k(t)\}$

The Optimum Demodulator for M-ary Signals in AWGN (7/14)

- Note that y_k=s_{mk}+n_k, k=1,2,...,N. Since the signal {s_m(t)} are deterministic, the signal components {s_{mk}} are deterministic. The noise components {n_k} are Gaussian distributed
- The mean values of $\{n_k\}$ are $E[n_k] = \int_0^T E[n(t)]\psi_k(t)dt = 0.$

Their covariance are

$$E[n_k n_m] = \int_0^T \int_0^T E[n(t)n(\tau)]\psi_k(t)\psi_m(\tau)dtd\tau$$

= $\int_0^T \int_0^T \frac{N_0}{2} \delta(t-\tau)\psi_k(t)\psi_m(\tau)dtd\tau$
= $\frac{N_0}{2} \int_0^T \psi_k(t)\psi_m(t)dt$
= $\frac{N_0}{2} \delta_{mk}$,

where δ_{mk} is the Kronecker delta. Note $\delta_{mk}=1$ when m=kand will otherwise be zero

The Optimum Demodulator for *M*-ary Signals in AWGN (8/14)

- The *N* noise components $\{n_k\}$ are zero-mean uncorrelated Gaussian random variables with a common variance $\sigma_n^2 = N_0/2$, and it follows that $f(\mathbf{n}) = \prod_{i=1}^N f(n_i) = \frac{1}{(\pi N_0)^{N/2}} e^{-\sum_{i=1}^N \frac{n_i^2}{N_0}}$
- The correlator output $\{y_k\}$ conditioned on the *m*th signal being transmitted are Gaussian random variables with mean

$$E[y_k] = E[s_{mk} + n_k] = s_{mk}$$

and equal variance

$$\sigma_y^2 = \sigma_n^2 = N_0/2.$$

Since the noise components $\{n_k\}$ are uncorrelated Gaussian random variables they are also statistically independent

The Optimum Demodulator for *M*-ary Signals in AWGN (9/14)

The conditional probability density functions (PDF's) of the variables (y₁,y₂,...,y_N)=y are simply

$$f(\mathbf{y}|s_m) = \prod_{k=1}^{N} f(\mathbf{y}_k | s_{mk}), \ m = 1, 2, ..., M$$

where

$$f(y_k \mid s_{mk}) = \frac{1}{\sqrt{\pi N_0}} e^{-(y_k - s_{mk})^2 / N_0}, \ k = 1, 2, ..., N$$

• We obtain the joint conditional PDF's as

$$f(\mathbf{y} \mid \mathbf{s}_{m}) = \frac{1}{(\pi N_{0})^{N/2}} \exp\left[-\sum_{k=1}^{N} (y_{k} - s_{mk})^{2} / N_{0}\right]$$
$$= \frac{1}{(\pi N_{0})^{N/2}} \exp\left[-\left\| \mathbf{y} - \mathbf{s}_{m} \right\|^{2} / N_{0}\right], \quad m = 1, 2, ..., M$$

We can show that no additional relevant information can be extracted from the remaining noise n'(t), i.e., E[n'(t)y_k]=0

The Optimum Demodulator for *M*-ary Signals in AWGN (10/14) $E[n'(t)y_{k}] = E[n'(t)(s_{mk} + n_{k})]$ $= E[n'(t)s_{mk}] + E[n'(t)n_{k}]$ $= E[n'(t)]s_{mk} + E[n'(t)n_k]$ $= E[n'(t)n_k]$ $= E\left[\left(n(t) - \sum_{i=1}^{N} n_{j} \psi_{j}(t)\right) n_{k}\right]$ $= E \left| n(t)n_k - \sum_{i=1}^N n_j n_k \psi_j(t) \right|$ $= \int_{0}^{T} E[n(t)n(\tau)]\psi_{k}(t)dt - \sum_{j=1}^{N} E(n_{j}n_{k})\psi_{j}(t)$ $=\frac{N_0}{2}\psi_{k}(t)-\frac{N_0}{2}\psi_{k}(t)$ = 0

The Optimum Demodulator for M-ary Signals in AWGN (11/14)

- Since n'(t) and {y_k} are Gaussian and uncorrelated, they are also statistically independent. All the relevant information is contained in the correlator output {y_k}
- Example 8.4.5. Consider an *M*-ary PAM signal set given by $s_m(t) = s_m \psi(t), \ 0 \le t \le T, \ m = 1, 2, ..., M$. The basis function is defined by $\psi(t) = \sqrt{1/T}, \ 0 \le t \le T$. The additive noise is a zeromean white Gaussian noise process with spectral density $N_0/2$. Determine the PDF of the received signal at the output of the demodulator and sketch the PDFs for the case M=4.
- The received signal is expressed as $r(t) = s_m \psi(t) + n(t).$

The Optimum Demodulator for *M*-ary Signals in AWGN (12/14)

• Example 8.4.5. (Cont'd) The output of the demodulator is

$$y(T) = \int_0^T r(t)\psi(t)dt = \int_0^T [s_m\psi(t) + n(t)]\psi(t)dt$$

where *n* is a zero-mean Gaussian random variable with variance $\sigma_n^2 = N_0/2$. Therefore, the PDF of $y \equiv y(T)$ is $f(y | s_m) = \frac{1}{\sqrt{\pi N_0}} e^{-(y-s_m)^2/N_0}, m = 1, 2, ..., M$

and $s_m = (2m - 1 - M)d$. The PDF's for M = 4 PAM are shown below



 $= s_m + n$,

Figure 8.41 PDF's for M = 4 received PAM signals in additive white Gaussian noise.

The Optimum Demodulator for *M*-ary Signals in AWGN (13/14)

Example 8.4.6. Consider the *M*=4 orthogonal PPM signal waveforms shown in Fig. 8.31(a), where the signal constellation points {*s_m*} are given by

$$s_{1} = (\sqrt{\mathcal{E}_{s}}, 0, 0, 0);$$

$$s_{2} = (0, \sqrt{\mathcal{E}_{s}}, 0, 0);$$

$$\vdots$$

$$s_{4} = (0, 0, 0, \sqrt{\mathcal{E}_{s}}).$$

The additive noise is zero-mean white Gaussian noise process with a spectral density $N_0/2$. Determine the PDF of the received signal vector y at the output of the demodulator, assuming that the signal $s_1(t)$ was transmitted

The Optimum Demodulator for *M*-ary Signals in AWGN (14/14)

• Example 8.4.6. (Cont'd) The received signal vector is

$$y = s_1 + n$$

= $(\sqrt{\boldsymbol{\mathcal{E}}_s} + n_1, n_2, n_3, n_4),$

where the noise components n_1, n_2, n_3, n_4 are mutually statistically independent, zero-mean Gaussian random variables with identical variance $\sigma_n^2 = N_0/2$

• The joint PDF of the vector components y_1, y_2, y_3, y_4 is $f(y_1, y_2, y_3, y_4 | \mathbf{S}_1) = \frac{1}{(\pi N_0)^2} e^{-\left[(y_1 - \sqrt{\mathbf{\xi}_s})^2 + y_2^2 + y_3^2 + y_4^2\right]/N_0}$